

(1) (1) Mode:
0: Normal (Open loop)
1: Position Lock
2: Speed Lock
2: PWD: -127 ~ 127
(3) Motor_Position_Point = Motor_Position_Point - byte0 + Motor_Position_Point - byte1 * 256 + Motor_Position_Point - byte * 65536 + Motor_Position_Point - byte3 * 16777216
(4) Motor_Position - MAX_Speed: -127 ~ 127
(5) Motor_Speed_Point: -127 ~ 127
(2) Voltage = ADC Value 8bits/255*3.3/0.16
(3) Voltage = ((ADC Value 12bits-L) + (ADC Value 12bits-H)*256)/255*3.3/0.16